

- M18 cylindrical type compatible with European Standards (CENELEC)
- Polarized retroreflective type capable of detecting mirrorlike objects
  - Thorough short circuit protection
  - Water resistance of IP 66 achieved by resin molding
  - Dramatic improvement of environment resistance including prevention of damage and falling off electronic components caused by vibration and enhanced robustness

# Type

Detection method	Detecting distance	Model		Operation made	Output made	Remarks
		NPN type	PNP type	Operation mode	Output mode	nemarks
Through beam	3m	CX-T3D	CX-T3DPN	Dark ON	Open collector	Infrared LED long distance type
Polarized retroreflective	2m	CX-M2RD	CX-M2RDPN	Dark ON		Red LED capable of detecting mirror-like objects
Diffuse reflective	100 mm	CX-R01	CX-R01PN	Light ON		Infrared LED
	300 mm	CX-R03V	CX-R03VPN	Light ON		Infrared LED type provided with adjustment for ease of fine detection

# Applications





## ■ Rating/Performance/Specification

Model	NPN type	CX-T3D	CX-M2RD	CX-R01	CX-R03V		
	PNP type	CX-T3DPN	CX-M2RDPN	CX-R01PN	CX-R03VPN		
Detection r	nethod	Through beam	Through beam Polarized retroreflective		Diffuse reflective		
Detecting distance		3m	2m *1	100mm *2	300mm *3		
Detection object		φ 15mm (or more) Opaque	Mirror-like / opaque / translucent	e / opaque / translucent Opaque / translucent			
Power supply		12 - 24V DC ±10% / Ripple 10% or less					
Current consumption	NPN type	Transmitter: 17 mA or less Receiver: 17 mA or less	20mA or less	17mA or less	20mA or less		
	PNP type	Transmitter: 17 mA or less Receiver: 23 mA or less	24mA or less	23mA or less	26mA or less		
Output mode	NPN type	Open collector Rating: sink current 100 mA (30 VDC) or less					
	PNP type	Open collector Rating: source current 100 mA (30 VDC) or less					
Operation mode		Dark ON		Light ON			
Response	time	0.35ms or less					
Operating angle		7° (at receiver)	10° (at reflector)				
Hysteresis				5% or less			
Light source (wavelength)		Infrared LED (950nm)	Red LED (700nm)	Infrared LED (880nm)			
Indicator		Transmitter: Power indicator (red LED)  Receiver: Light reception indicator (red LED)	Operation indicator (red LED)				
Volum	ne				Sensitivity adjustment		
Short circuit protection		Provided					
Material		Lens: Polycarbonate	Lens: Acrylic	Lens: Polycarbonate			
		Case: Polycarbonate	Case: Polycarbonate	Case: Polycarbonate			
Connection		Attached cable (outer diameter: 4 mm) Transmitter: 0.2 mm² 2 cores 2 m (gray) Receiver: 0.2 mm² 3 cores 2 m (black)	Attached	,			
Weight		Transmitter: Approx. 65 g Receiver: Approx. 65 g	Approx. 65 g				
Accessory			K-7 reflector				
		Operation manual					

- \*3 With 100 x 100 mm white drawing paper
- The detecting distance and detection object of retroreflective types varies, depending on reflector types combined with the sensor.
  The detecting distance is the range which you can set for the reflector. The sensor can detect an object even in extremely short range.
  The detecting distance of diffuse reflective type varies, depending on transmittance of the detection object. Please be sure to check the detection beforehand.

# Environmental Specification

	•		
Ambient light	5,000 lx or less		
Ambient temperature	-25 - +55°C (non-freezing)		
Ambient humidity	35 - 85%RH (non-condensing)		
Protective structure	IP66		
Vibration	10 - 55 Hz / 1.5 mm double amplitude / 2 hours each in 3 direction		
Shock	100 m/s² / 3 times each in 3 directions		
Dielectric withstanding	500 VAC for 1 minute		
Insulation resistance	1,000 VDC, 20 M O or higher		

# Applicable power supply unit PS Series

High capacity of 200 mA at 12 VDC



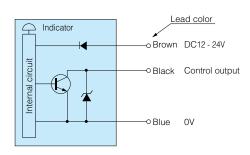
(General-purpose type) PS3N (Multifunctional type)

PS3N-SR PS3F PS3F-SR

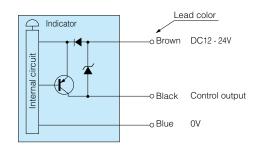


# ■ Input/Output Circuit and Connection

NPN output



PNP output



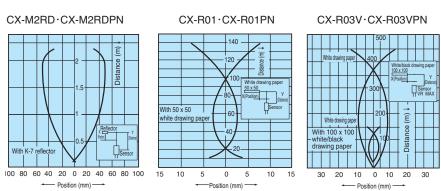
• Response Curves: Detecting Position

- The output transistor turns off when load short circuit or overload occurs. Check the load and turn the power back on.
- A through beam transmitter has only power supply cables (brown: 12-24DVC, blue 0DVC).

# Performance Curves (Typical)

• Response Curves : Beam Pattern

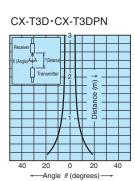
CX-T3D·CX-T3DPN



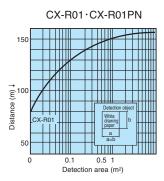
Response Curves: Tilt Angle

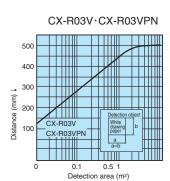
Position (mm)

50



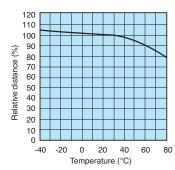
Response Curves: Target Size



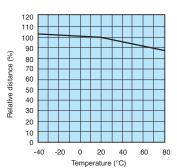


#### Response Curves : Ambient Temperature

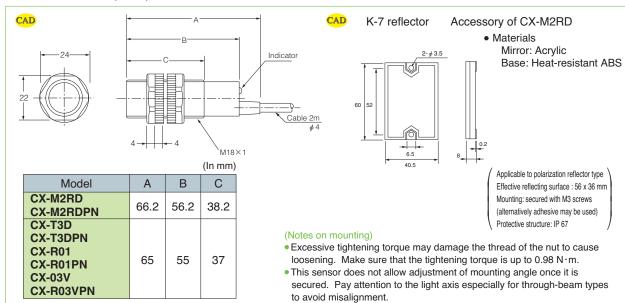
CX-M2RD CX-M2RDPN







## Dimensions (in mm)



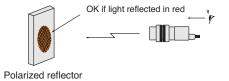
## Setting

## (Through beam type)

- For light axis alignment, swivel the receiver vertically and horizontally to install it at the center of the area in which the light reception indicator (red LED) is illuminated for the individual direction.
- Repeat activation and deactivation to check the operation.

# (Polarized retroreflective type)

• Arrange the sensor in line with the reflector. Swivel the sensor vertically and horizontally with reference to the reflector, use the operation indicator to check the area in which the sensor is activated (indicator goes out) and install the sensor at the center of the area. Taking advantage of the red light spot on the reflector seen from behind the sensor allows easy setting.



# (Diffuse reflective type)

- Set the sensor so that the operation indicator (red LED) is illuminated with the detection object placed at a given position and not illuminated with the object removed.
- Bring any background of the detection object as far away as possible or use black surface with low reflectance.
- The detecting distance depends on the surface condition of the detection object. This sensor is not provided with a sensitivity adjustment volume and needs to be adjusted for stable operation by changing the distance, angle, background object, etc.

## (Diffuse reflective type with adjustment)

- Adjustment with any light-reflecting object in the background
- (1) Place the object to be detected in a given position, turn up the sensitivity adjustment volume (SENS) gradually from the minimum (MIN) and find the point at which the operation indicator (red LED) is illuminated (Point A).
- (2) Remove the object, turn down the sensitivity adjustment volume gradually from the maximum (MAX) and find the point at which the operation indicator (red LED) goes out (Point B). (If the operation indicator is not illuminated even at MAX, MAX is regarded as Point B.)
- (3) Set the volume at midway between Points A and B.





